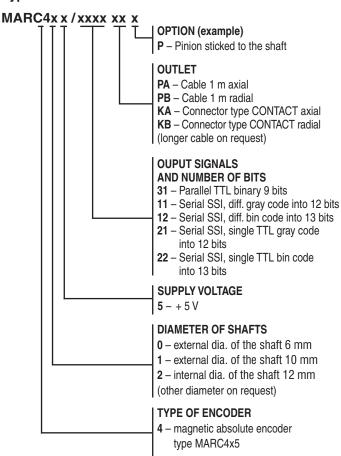


Magnetic absolute encoders MARC405, 415 and 425

MARC405 – synchro flange, external diameter of the shaft 6 mm
MARC415 – clamping flange, external diameter of the shaft 10 mm
MARC425 – stator coupling, blind hollow shaft internal diameter 12 mm

The magnetic single turn absolute rotary encoders type MARC405, 415 and 425 working on magnetic Hall Effect principle. The encoder converts rotary motion to electrical signals. Electrical signals provide information of bilateral position of two mechanical parts, angle turn or rotary motion. A typical use is in conjunction with digital control system or drivers for control of the electric motors.

Type identification



Technical data

ELECTRICAL DATE / TYPE	MARC405, 415, 425	
Positions per rotation	into 13 bits (into 8192 pos.)	
Supply voltage max. U _N (V)	+ 5 ± 5%	
Supply current max. I _N (mA)	50	



Mechanical data and working conditions

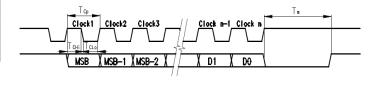
10000 min1
40000 rad.s ⁻²
10 g.cm ² ± 10 %
10g _n (10 to 2000 Hz)
50g _n (100 ms)
20/40 N
50/60 N
– 25° to + 80° C
max. 95 % / max. 40g.m ⁻³
73,3 to 126,6 kPa
IP65
ca. 0,25 / 0,35 kg
50 m

Output signals MARC405 / MARC415 / MARC425

- 31 Parallel TTL binary code for encoders with resolution into 9 bits (512 positions).
- 11 Serial SSI, differential CLOCK/DATA signals (RS422), gray code into 12 bits (4096 pos.).
- 12 Serial SSI, differential CLOCK/DATA signals (RS422), bin code into 13 bits (8192 pos.).
- 21 Serial SSI, single TTL CLOCK/DATA signals, gray code into 12 bits (4096 pos.).
- 22 Serial SSI, single TTL CLOCK/DATA signals, bin code into 13 bits (8192 pos.).

SSI communication

Parameter	Symbol	Min	Max	Unit
Clock period	T _{Cp}	250	2xT _m	μs
Clock High	T _{CHi}	25	T _m	μs
Clock Low	T _{CLo}	25	T _m	μs
Monoflop time	T _m	16	20,5	μs



Description of connection elements MARC405, 415 and 425

Pin connector type CONTACT	Colors of connection cable	Significance MARC405, 415 and 425
1	Grey	SSI – CLOCK-
2	Pink	SSI – DATA-
3	Blue	INC – Signal Z (1)
4	Violet	SSI – DATA+
5	Yellow	INC – Signal A (1)
6	White	SSI – CLOCK+
7	-	NC
8	Green	INC – Signal B (1)
9	Shield	Shield
10	Black	GND
11	Brown	GND
12	Red	$V_{cc} + 5 V$

(1) Only on request

Assembly

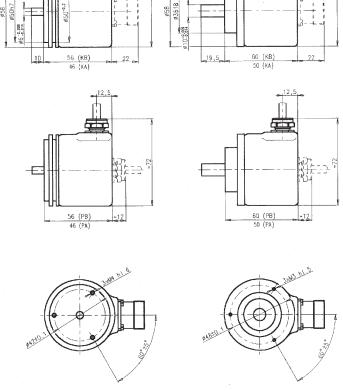
The encoder MARC405 is installed into appropriate equipment using 3xM4 screws or a groove. The position of the shaft is explicitly determined by a fitted diameter of 50h7. The encoder MARC415 is installed using 3xM3 screws and the position of the shaft is explicitly determined by a diameter of 36f8. It is recommended to use appropriate homokinetic connections (see the catalogue sheet "Accessories"). The encoder MIRC425 with stationary coupling is installed on the shaft of appropriate equipment and tightened by two imbus screws M4. Afterwards the encoder is turned to the required position and the stationary coupling is fixed by two or four (optimal) screws M3. The connection has to be designed so as to

avoid exceeding the maximum admissible radial or axial load applied to the shaft and it is necessary to keep the connection aligned. The cable of the MARC4xx encoder must be fastened so as to avoid stress on the encoder by is own weight. In wet environments with running or splashing water it is recommended not to position the MARC4xx encoders with the shaft pointing upwards. When temperature is less then –5°C cable must be fixed.

Dimensioned drawing

MARC405

MARC415



How to order?

Please indicate encoder type, number of impulses per rotation, outlet, number of pieces, delivery term and other non-standard features. Connecting cable and homokinetic diaphragm couplings can be ordered as well [see Accessories catalogue list].

Example

25 pcs MARC425/11KB. Delivery term - two weeks.

MARC425

